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Sir:

Transmitted herewith for filing is the  
Patent Application of:

Inventors: Stephen D. Julstrom  
Robert B. Schulein

For: **DIRECTIONAL MICROPHONE ASSEMBLY  
FOR MOUNTING BEHIND A SURFACE**

Case Docket No. 12078US01

Enclosed are:

- X 6 sheets of drawing (informal)
- X 22 pages of specification, 23 pages of claims, and
- X 1 page of Abstract.
- Verified Statement (Declaration) Claiming Small Entity Status (37 C.F.R. 1.9(F) and 1.27(c)) Small Business Concern
- X Declaration and Power of Attorney (unsigned)

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**CLAIMS AS FILED**


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Respectfully submitted,

**McANDREWS, HELD & MALLOY, LTD.**

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**DIRECTIONAL MICROPHONE ASSEMBLY  
FOR MOUNTING BEHIND A SURFACE**

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**CROSS-REFERENCE TO RELATED APPLICATIONS**

**NOT APPLICABLE**

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**STATEMENT REGARDING FEDERALLY SPONSORED  
RESEARCH OR DEVELOPMENT**

**NOT APPLICABLE**

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**BACKGROUND OF THE INVENTION**

20 The present invention relates to directional microphone assemblies, and particularly to those which may be used in applications which benefit from minimum visual intrusion. A primary example of these applications is use in vehicle cabins for speech pickup for hands-free telephony and other communication and control applications.

Both omnidirectional and directional microphones have been used for this purpose. These are generally mounted on interior surfaces, most typically at a forward, central headliner position or near the top of the driver side roof-support pillar. Omnidirectional microphones have also

25 been mounted behind such surfaces, with sound entering through a relatively small surface hole or group of holes or slots. This behind-the-surface mounting is aesthetically preferable to over-the-surface mounting and eliminates the need for designers to consider microphone

30 styling and color.

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Directional microphones can produce significant performance advantages over omnidirectional ones in the vehicle environment, however, and are therefore preferable. Compared to an omnidirectional microphone, an optimally positioned, well-designed, surface-mounted first-order directional microphone can produce a several decibel advantage in the ratio of speech pickup to general road noise, and an even greater advantage in rejection of localized ventilation noises and return telephony audio.

Although encased directional microphones, where the microphone elements are contained within mostly acoustically opaque housings, are presently available for other applications, most notably for use in hearing aids and, more recently, in some portable telephones and computer monitors, these prior art approaches have requirements and characteristics which make them less than optimum for subsurface applications such as the just described vehicle use. A typical prior art approach is shown cutaway in FIG. 1. A small (approximately 1 cm tall) electret microphone element 11 is mounted perpendicularly behind a thin surface 13. The front of the element diaphragm acoustically couples through tube 15 and surface hole 17 to the acoustic pickup region 19. Similarly, the rear of the element diaphragm acoustically couples through tube 21 and surface hole 23 to pickup region 19. Acoustic resistor 25 in tube 21, in conjunction with the enclosed rear volume 27 behind the element diaphragm, form a low-pass filter/delay for sound entering hole 23. This delay, in conjunction with the dimensions of the front and rear sound entry paths and the spacing distance between entry holes 17 and 23, forms a first-order directional pickup pattern in the pickup region which is directed along a line from rear entry hole 23 to front entry hole 17.

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This prior art approach can be implemented to operate effectively over a useful frequency range. Its acoustical characteristics are, however, critically dependent on the individual and relative acoustical characteristics of the front and rear sound entry paths.

- 5 Included in these paths are the mounting surface 13, surface holes 17 and 23, and anything which may be placed in front of them. Were such an assembly to be installed behind an automotive interior surface, the sound entry paths would be modified by considerable additional surface thickness with varying additional entry hole sizes and possibly
- 10 by acoustically semi-transparent decorative covering material. These additional acoustical elements would degrade each of the front and rear sound entry paths differently, since each presents different acoustic impedance at entry holes 17 and 23. The driving force on the element diaphragm is derived from the difference of the pressures on its front
- 15 and rear sides and may have a magnitude which is only a relatively small percentage of the individual front and rear pressure magnitudes. Relatively small unbalanced changes in the front and rear pressures can, then, result in much larger relative changes in the net diaphragm driving force, causing the mounted microphone assembly pickup
- 20 characteristics to suffer severe degradation.

- What is needed, then, is another approach to creating a subsurface directional microphone. It should be capable of attachment behind an interior surface, with acoustic entry provided by relatively small and unobtrusive openings. It should exhibit a high degree of
- 25 insensitivity to the characteristics of the acoustic entry paths through the surface.

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Therefore, an object of the present invention is to provide a directional microphone assembly which can be unobtrusively mounted behind a surface.

Another object is to provide such an assembly which exhibits  
5 greatly reduced sensitivity to variations in the acoustical coupling through the surface.

Another object is to provide such an assembly with reduced sensitivity to variations in microphone element characteristics.

Another object is to provide such an assembly with reduced  
10 sensitivity to very low frequency inputs.

Another object is to provide such an assembly with extended high frequency response.

A further object is to provide such an assembly which also includes an additional output with more extended low frequency  
15 response and reduced directionality.

Yet another object is to provide a similar assembly which can provide two or more directional patterns aimed in different directions.

#### BRIEF SUMMARY OF THE INVENTION

20 These and other advantages and novel features of the present invention, as well as details of an illustrated embodiment thereof, will be more fully understood from the following description and drawings.

These and other objects are achieved in the disclosed embodiments of the invention through the use of an array of two or  
25 more omnidirectional microphone elements, each with their diaphragms acoustically coupled through openings in the microphone assembly case and in the mounting surface to the pickup region on the other side of the surface. These acoustical coupling paths are

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acoustically sealed such that significant microphone element excitation comes only from sound entering from the pickup region.

The output signals of two such microphone elements are combined to create a first-order directional pickup pattern. In a possible variation, the difference of the two signals is taken to create a bidirectional pickup pattern. One of the signals can be delayed before the difference is taken, allowing first-order patterns other than bidirectional to be created.

The described structure is considerably less sensitive than the prior art to coupling degradations from the mounting surface for several reasons. First, the coupling from the element diaphragm to the surface opening is more direct, presenting a simpler acoustic impedance to the opening. Second, the impedance presented to each opening is identical. Assuming substantial similarity in the openings, some small degradation of frequency response and level might be experienced with, for example, a semi-transparent cloth covering, but potentially much larger response and pattern variations resulting from differing degradations of amplitude and phase response at each coupling is avoided. Third, assuming that well-controlled directionality is not required at very high frequencies, the microphone elements and their openings can be positioned farther apart than is practical with the prior art. The desired sound pickup can then result in larger pressure differences at the microphone elements in comparison to degradation-related differences than would otherwise occur. For a pickup pattern between cardioid and supercardioid, a preferred embodiment employs a spacing distance between the openings of, for example, 3.5 cm, allowing the maintenance of good directionality to past 3 kHz.

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The present invention also includes several features to minimize the microphone assembly's sensitivity to the effects of amplitude and phase response mismatches between the elements. These effects have generally been overlooked or not fully addressed in prior art

5 descriptions of differenced microphone arrays. The present invention employs the maximum practical inter-element spacing to maximize the desired acoustical signal differences while minimize any degradations which occur as a result of coupling or mismatches in the elements.

Since the greatest mismatch-induced response and pattern errors appear

10 in the lower frequencies where the desired acoustical signal differences are smallest, aberrant behavior from the resultant exaggerated low-frequency responses is minimized by the inclusion of a high-pass filter following the pattern-generating differencing operation. Such a filter clearly demarcates the lower end of the useful frequency range. This

15 filter may also be conveniently used to shape the assembly's frequency response just above this lower end. Very low-frequency transient problems may also be minimized by the use of matching high-pass filters applied to the microphone element signals before significant signal amplification takes place. Finally, since the greatest source of

20 inter-element phase mismatch results from differences in the low-frequency extension of the elements' low-frequency cutoffs, the phase mismatch error source can be minimized by employing microphone elements with well-controlled, very low, low-frequency cutoffs.

In a related embodiment, at least three microphone elements are

25 used to generate at least two directional patterns aimed in different directions. In the case of three elements being used to create two patterns, one of the elements is employed in common to generate both patterns. An automatic selection process based on the acoustic input to



the microphone assembly may be employed to selectively combine the patterns.

5 This output may be formed in relation to a local ground which is separated from the main output ground by an isolating impedance and with an output impedance that is much higher than the expected load impedance.

BRIEF DESCRIPTION OF THE SEVERAL VIEWS  
OF THE DRAWINGS

FIG. 2 is a partial top view of a vehicle cabin showing typical  
15 positioning of microphone assemblies of the present invention.

FIG. 4 is a block diagram of a microphone assembly signal  
20 processor built in accordance with the present invention. .

FIG. 6 is a graph showing the added effect of an underdamped  
25 300 Hz high-pass filter of the present invention on the response of  
FIG. 5.

FIG. 7 shows detail of one embodiment of a pattern generating circuit block built in accordance with the present invention.

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FIG. 8 shows detail of another embodiment of the pattern-generating circuit block built in accordance with the present invention.

FIG. 9 shows detail of the differencing circuit built in accordance with the present invention.

5           FIG. 10 shows multiple microphone assemblies and an automatic selector/combiner in accordance with the present invention.

FIG. 11 shows one embodiment of a combination assembly of the present invention arranged to provide full left-right coverage.

10           FIG. 12 shows an alternate embodiment of the combination assembly of the present invention.

FIG. 13 shows an application of a combination assembly in a vehicle cabin in accordance with the present invention.

FIG. 14 shows a detailed block diagram of a combination assembly of the present invention.

15           FIG. 15 shows detail of one embodiment of additional output circuitry built in accordance with the present invention.

#### DETAILED DESCRIPTION OF THE INVENTION

20           FIG. 2 illustrates a typical application for the present invention. A partial top view of a vehicle cabin 31 is shown with a left-hand driver 33 and a right-hand passenger 35. For right-hand drive vehicles, the driver and passenger positions are interchanged. A microphone assembly 37 of the present invention intended for speech  
25   pickup for hands-free telephony and other communication and control applications is shown mounted to and behind the cabin interior trim roof headliner or behind the surface of a headliner-mounted accessory console. For a telephony application, the assembly should generally

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provide a well-controlled directional pattern and frequency response over a frequency range of approximately 300 Hz to 3kHz. For applications such as speech recognition and in-car speech reinforcement, useful response may need to extend to 5 kHz or  
5 beyond, but with some relaxation of directional pattern accuracy being acceptable. Within the constraint that the directional pattern must ordinarily be developed aiming parallel to the mounting surface, the horizontal aiming direction is generally in the direction of the driver. Choosing an optimum aiming direction and polar pattern requires a  
10 compromise among several factors. Often, a polar pattern between cardioid and supercardioid which is aimed slightly behind an average driver's head position provides the best balance between pickup of driver speech from the variety of driver head positions and rejection of dashboard-originating ventilation, defogger fan noises and return  
15 telephony audio. This aiming angle is typically about 45 degrees away from the cabin centerline, towards the driver. To improve pickup of front-seat passenger speech, another microphone assembly 39 may be symmetrically positioned towards the passenger. Automatic microphone assembly signal combining based on speech input to the  
20 assemblies may be employed to prevent signal-to-noise degradation of roughly 3 decibels compared to each individual microphone which would occur with the simple addition of the assembly signal outputs. An appropriate combining method is described in U.S. Pat. No. 5,673,327, issued to Stephen D. Julstrom and entitled "Microphone  
25 Mixer", which patent is incorporated herein by reference. Alternately, if only the single microphone assembly 37 is used and secondary, albeit reduced quality, coverage of the passenger is still desired, an angling of about 30 degrees away from the centerline may be more

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appropriate to avoid placing the passenger too far off the main pickup axis of the assembly.

Another possible installation is shown by microphone assembly 41 mounted behind the interior surface covering of driver-side roof support pillar 43. In vehicles with more steeply swept-back windshields, this positioning can provide a close microphone positioning to the driver's mouth, along with reasonable rejection of dashboard-originating interfering noises. To improve pickup of front-seat passenger speech, another microphone assembly 45 can be similarly mounted to passenger-side roof support pillar 47, and automatic signal combining applied.

As will be discussed in relation to FIG. 10, additional microphone assemblies beyond two may also be employed to facilitate even more complete coverage of a vehicle cabin. Automatic combining becomes more desirable as the number of microphone assemblies employed increases.

FIG. 3 shows a cutaway diagrammatic view of a two-microphone element embodiment of the present invention mounted behind an acoustical barrier such as a vehicle interior trim surface. This embodiment is representative of an assembly appropriate for mounting in the positions described in relation to FIG. 2. Omnidirectional electret condenser microphone elements 51 and 53 are positioned with their diaphragms and sound entries facing the inside surface of the microphone assembly case 55 and the rear of mounting surface/acoustical barrier 57. Sound is coupled to the diaphragms from pickup region 59 through holes 61 and 63 in case sealing gaskets 65 and 67, acoustically semi-transparent protective screens 69 and 71, holes 73 and 75 in assembly case 55, holes 77 and 79 in mounting

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sealing gaskets 81 and 83, holes 85 and 87 in mounting surface 57, and possibly acoustically semi-transparent decorative covering 89. With the depicted structure, sound can be coupled from the pickup region through unobtrusive openings in the mounting surface to the

5 microphone element diaphragms while sealing out undesirable acoustic input from behind the surface. The acoustical openings through the assembly case and mounting surface may also each consist of multiple holes, slots, rings, or other patterns which exhibit reasonable acoustical openness. Other structures may be envisioned which may differ in

10 detail from that depicted in FIG. 3, but which still achieve the stated goal of through-the-surface coupling and sealing. These are not to be construed as being outside the scope and spirit of the present invention.

Holes 85 and 87 are located in the mounting surface with an inter-hole spacing distance "d". Most generally, this will also

15 correspond to the distance from center-to-center of the microphone element diaphragms.

Microphone elements 51 and 53 produce microphone element output signals 91 and 93, respectively, which constitute the inputs to signal processor 95. Processor 95 produces the assembly output signal

20 97 from these inputs.

Several aspects of the depicted structure are worth noting. First, the acoustical coupling characteristics from the pickup region to the microphone element diaphragms are likely to vary considerably from application to application, depending on the exact dimensions of

25 the openings and the characteristics of the cloth covering, if present. Second, the acoustical paths from the pickup region to the microphone element diaphragms are still simpler and more direct than would be the case if the prior art example were similarly mounted behind such a

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depicted surface. Third, in direct contrast to the prior art, the acoustical couplings to each diaphragm, including the terminating impedance at each diaphragm, remain matched to each other, independent of the details of the specific mounting. This last aspect is significant because, as will be discussed in relation to FIGS. 4 - 9, the directional assembly output signal 97 is generated based on the instantaneous difference in pressure at each diaphragm. Acoustical signal attenuations occurring in the acoustical couplings are reflected in corresponding attenuations in the assembly output. However, identical attenuations and phase shifts in the couplings do not result in exaggerated variations in the assembly output due to the differencing operation or in polar pattern distortions.

For example, tests were conducted on an assembly with a spacing distance of 4 cm and a generated supercardioid pickup pattern. Coupling through 1/5-inch diameter, 1/4-inch deep mounting surface holes resulted in barely detectable changes in response and polar pattern. Adding fairly thin, but visually opaque cloth material from a luxury car roof pillar covering still resulted in barely detectable changes. Substituting similar material with a thin foam backing or a more acoustically opaque cloth from another car resulted in about 2 decibels of on-axis sensitivity loss in the mid frequencies, but still very small change in the polar patterns. A modest deterioration of the pattern was just becoming evident in the 300 to 500 Hz range. These results are very good in comparison to what could be expected with the application of the prior art to a similar mounting, and exemplify the desirability of the invention in such subsurface applications.

Signal processor 95 is further detailed in block diagram form in FIG. 4. Microphone element output signals 91 and 93 enter pattern

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generating circuitry 101 which generates a directional pickup pattern one order higher than that of either of the matched microphone elements. In a free-space configuration, first-order directional microphones could theoretically be used, resulting in a second-order pickup pattern. In the subsurface mounting just described, omnidirectional elements are used, which will then result in a first-order pickup pattern appearing at pattern signal output 103. Next, pattern signal 103 passes into high-pass filter 109, which finally produces assembly output signal 97. The high-pass filter 109 clearly demarcates the lower end of the useful bandwidth. The benefits of this filter become evident through examination of the effects of likely mismatch errors between the two microphone elements. As mentioned above, these effects have been generally overlooked or not fully addressed in prior art descriptions of different microphone arrays.

In another embodiment, additional output circuitry 105 may be included to produce additional output 107 from either of the individual microphone element output signals. This additional output 107 may most often be used for noise-sensing functions. It will typically have an extended low-frequency response in comparison to the main directional assembly output 97, perhaps down to 100 Hz or lower. The main directional assembly output 97 does not necessarily need and, as will be discussed below in relation to FIGS. 5 and 6, should not generally be allowed to have extended low-frequency response.

Errors in the microphone assembly frequency response and polar pattern resulting from mismatches in microphone element amplitude and phase responses become greater as the frequency is lowered. Assuming omnidirectional microphone elements with basically flat frequency responses, the primary source of variations in

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the elements' lower frequency phase responses may be regarded as variations in their lower frequency amplitude responses. The required elements exhibit a flat frequency response down to a low frequency -3 decibel cutoff frequency which is determined primarily by a pressure-equalizing barometric leak, as is known in the art. There is also a typically smaller contribution to the low-frequency roll-off from the interaction of the element's diaphragm capacitance and the input impedance of impedance converter circuitry. Assuming that these -3 decibel cutoff frequencies are well below the anticipated useful frequency range of the array, analysis shows that the inter-element phase mismatch at frequencies within the useful frequency range can be considered to be approximately determined solely by the difference between the elements' cutoff frequencies.

FIG. 5 illustrates the effects of 20 Hz low-frequency cutoff frequency mismatches on the on-axis frequency response from 1 Hz to 10 kHz of a two-element assembly with a spacing distance between the acoustical openings of 3.5 cm and a nominal polar pattern between cardioid and supercardioid. The curve 201 is the ideal response from two perfectly matched elements. The curve 203 results from a +20 Hz cutoff frequency mismatch; that is, the front element in relation to the directional pattern has a 20 Hz cutoff and the rear element is flat to 0 Hz. The curve 205 results from the opposite mismatch. Similar results would be obtained from, for example, paired 10 and 30 Hz cutoffs or paired 25 and 45 Hz cutoffs at frequencies significantly above these cutoffs.

It is evident from the curves that even small mismatches in the elements result in greatly exaggerated low-frequency responses. These become even worse if equalization is applied towards flattening the



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nominal response curve. The phase mismatches can also totally alter the directional pattern. The pattern at the curve 205 null at about 140 Hz, for example, becomes a rear-facing cardioid. The excess uncontrolled low-frequency response can be very problematic in light  
5 of the high levels of low-frequency acoustic energy present in many applications, especially when gain is applied to bring the assembly output up to useful levels.

Three primary remedies for the matching problem can be applied in the present invention. First, as will be discussed in relation  
10 to FIG. 9, gain adjustment means are provided to allow close matching of the effective midband amplitude sensitivity of the microphone element signals before the differencing operation. Second, microphone elements are employed which inherently have close matching of their low-frequency cutoff frequencies. This can be achieved by employing  
15 elements with fairly low and well controlled cutoffs in, for example, the range of 20 Hz to 40 Hz, or with very low, but more poorly controlled cutoffs in, for example, the range of 5 Hz to 25 Hz, or, simply, lower than 20 Hz. These represent cutoff mismatches of no greater than 1/15 of the 300 Hz lower frequency limit of the useful  
20 assembly frequency range. Usable assemblies could still be made with cutoff mismatches as high as 1/5 of the useful frequency range lower limit, but the tighter tolerances are much more desirable. Third, a high-pass filter is included following the pattern-generating differencing operation which clearly demarcates the lower end of the  
25 useful frequency range. FIG. 6 shows the effect of adding a second-order 300 Hz high-pass filter to the three curves of the previous figure. The curves demonstrate the benefit of essentially eliminating the

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troublesome uncontrolled low-frequency response before it is further amplified and input to following systems.

The particular second-order high-pass filter applied in FIG. 6 is underdamped, with a damping factor of 0.27. This gives a boost at the  
5 300 Hz corner frequency of 5.3 dB. This helps to shape the desired frequency response within the useful frequency range to more closely match an ideal narrowband speech communication response. The graph also shows a falloff in response above 3 kHz. This is determined by the spacing distance between the acoustical openings  
10 and by the nominal generated directional pattern, as will be discussed further in relation to FIG. 8.

FIG. 7 shows detail of one embodiment of the pattern generating circuitry 101 from FIG. 4. Microphone element output signals 91 and 93 enter high-pass roll-off filters 111 and 113,  
15 respectively, which produce rolled-off signals 115 and 117, respectively. Signals 115 and 117 enter differencing circuit 119, which then produces pattern signal 103. In this case, the directional pattern generated from omnidirectional microphone element signal inputs is bidirectional. The roll-off filters' function is to greatly  
20 attenuate very low-frequency signals from the extended frequency-response microphone elements before they are further processed or any significant gain is applied. This greatly reduces the microphone assembly's sensitivity to large, very low frequency transients. To provide significant benefit, these filters will have corner frequencies  
25 above the low-frequency cutoff frequencies of the microphone elements.

In an analog circuit implementation, the roll-off filters will generally be first-order, reasonably closely matched, and have corner

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frequencies somewhat below the lower limit of the useful frequency range. All these things contribute to minimizing the introduction of any phase mismatches to the front and rear element signals. Just a few degrees of mismatch can seriously upset the response and polar pattern at the lower limit of the useful frequency range. For a 300 Hz lower limit, a roll-off corner frequency of 50 Hz to 100 Hz would be typical. Even greater very low-frequency attenuation could be achieved at these circuit points with second or higher order filters such as that typically employed in high-pass filter 109 in FIG. 4, but an analog implementation of two steep roll-off filters would have great difficulty maintaining the desired tight phase-matching. Well-matched, gradual roll-off filters with corners between the microphone element low-frequency cutoffs and the lower limit of the microphone assembly's useful frequency range immediately applied to the element signals and a steeper high-pass filter following the differencing operation are appropriate design choices for an analog implementation. Alternatively, all or a portion of the microphone assembly signal processing could be implemented digitally. Analog-to-digital conversion could take place with microphone element output signals 91 and 93, rolled-off signals 115 and 117, or pattern signal 103. Roll-off filters 111 and 113 would be perfectly matched if implemented digitally, allowing more freedom in their design. However, placing the filters before the A-to-D conversion would protect the converter from excessive very low-frequency signals.

FIG. 8 shows detail of another embodiment of the pattern generating circuitry 101 from FIG. 4. This circuitry differs from the pattern generating circuitry of FIG. 7 only in the addition of delay 121, which delays rolled-off signal 117 to produce delayed signal 123.

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Delayed signal 123 is then input into differencing circuit 119, along with rolled-off signal 115. The inclusion of delay 121 allows first-order patterns other than bidirectional to be generated. For a first-order pattern defined by  $1 - B + B \cos(\theta)$ , the required delay is  
5 given by  $(d/c) \cdot (1 - B)/B$ , where  $d$  is the acoustical opening or inter-element spacing distance and  $c$  is the speed of sound. For a pattern between cardioid and supercardioid,  $B = 0.586$ , and with  $d = 3.5$  cm, the delay 121 should be approximately 72 usec. This delay may be implemented digitally, or approximated in analog circuitry over the  
10 useful directional frequency range with an all-pass filter or a low-pass filter. The on-axis response curves of FIGS. 5 and 6 were generated with a critically-damped, second-order low-pass filter having a corner frequency of 4.45 kHz. The low-pass filter exhibits an advantage over the all-pass filter or the pure delay in that deep high-frequency  
15 response nulls are avoided. Instead, the directional pattern blends smoothly to omnidirectional above the low-pass corner frequency. The net result is a microphone assembly which exhibits excellent pattern control and directivity relative to typical use angles of 30 to 60 degrees off-axis (a talker will not be exactly on-axis to a surface-mounted  
20 microphone) over a useful frequency range of 300 Hz to 3 kHz, usable response and directivity up to 5 kHz, and usable frequency response up to the upper limit of the microphone elements and their acoustical coupling.

Employing a narrower element spacing distance would allow  
25 the maintenance of good directivity to higher frequencies, but this is not necessary in anticipated applications and would compromise other benefits. Maintaining the widest spacing possible within the constraint of maintaining good directivity up to an upper frequency limit

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minimizes the assembly's sensitivity to any mismatches in the  
acoustical coupling differences or the microphone elements. The  
largest possible element spacing distance creates the largest possible  
inter-element pressure differences from the desired sound pickup, and  
5 thus minimizes the relative sensitivity to mismatch errors. The polar  
pattern-determining factor B and the wavelength W of an upper  
frequency limit for good directivity set the spacing distance  
approximately according to the formula  $d = K \cdot W \cdot B$ . K may  
optimally be about 1/2, but could vary over the range of 1/3 to 4/5  
10 while still maintaining reasonable results. A K of less than 1/5 may  
exhibit excessive sensitivity to mismatches to allow a useful working  
frequency range.

FIG. 9 shows detail of the differencing circuit 119 from FIGS.  
7 or 8. One input to differencing stage 125 comes from rolled-off  
15 signal 115 while the other comes from either rolled-off signal 117 or  
delayed signal 123. Interposed in these input paths are gain adjusters  
127 and 129. Either or both of these may be employed to trim out  
midband amplitude sensitivity differences in the two associated  
microphone elements to ensure precise matching of the effective  
20 electroacoustic sensitivities applied to the differencing stage.

As mentioned in relation to FIG. 2, two or more microphone  
assemblies may be employed to facilitate more complete coverage of a  
vehicle cabin or other pickup space. Automatic combining becomes  
desirable as microphone assemblies are added to avoid degradation in  
25 the signal-to-noise ratio of the combined output. FIG. 10 illustrates  
four microphone assemblies 131, 133, 135, and 137 sending their  
output signals to automatic selector/combiner circuitry 139, which  
outputs combined signal 141. The selector combiner/circuitry may

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advantageously be of the type described in the previously referenced Julstrom patent.

Referring again to FIG. 2, microphone assemblies 37 and 39, if used together, provide excellent coverage of the front seat, for driver  
5 and central and side passenger positions. They may be positioned very close to each other, near the vehicle centerline, and each angled outwards about 45 degrees. FIG. 11 shows a combination assembly 143 arranged to perform a similar function, but with a rear microphone element 145 which is common to both left-angling pattern generation  
10 circuitry which also employs microphone element 147 and right-angling pattern generating circuitry which also employs microphone element 149. The left and right-angling patterns are angled outwards from each other by an included angle  $\phi$ . If the left-angling pattern is described by  $1 - B + B \cdot \cos(\theta)$ , then the right-angling pattern can  
15 be described by  $1 - C + C \cdot \cos(\theta + \phi)$ . Most typically, the two patterns will be the same and B and C will be equal.

FIG. 12 shows an alternate embodiment of combination assembly 151. Here, the common microphone element is front element 153, which forms a left-angling pattern with element 155 and a  
20 right-angling pattern with element 157. In either combination assembly, additional patterns could be developed from the available elements, but the left and right-angling ones described are generally useful in anticipated applications. The outputs of the two pattern generating circuits may optimally be combined with an automatic  
25 selector/combiner, which would generate one or more intermediate patterns that are combinations of the basic left and right-angling ones.

FIG. 13 shows an application of combination assembly 143 in vehicle cabin 31. Both driver 33 and passenger 35 are well-covered,

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and rejection of interfering dashboard-originating noises is maintained in all conditions of the automatic selector/combiner.

FIG. 14 shows a detailed block diagram of combination assembly 143. The electrical signal sources are microphone elements 145, 147, and 149. Included are three roll-off filters 161, 163, and 165 which serve the same function as those described in relation to FIG. 7, a delay 167 which serves the same function as that described in relation to FIG. 8, up to four gain adjusters 169, 171, 173, and 175, two differencing stages 177 and 179 which serve the same functions as those described in relation to FIG. 9, high-pass filters 181 and 183 which serve the same function as those described in relation to FIG. 4, an automatic selector/combiner 185, and additional output circuitry 187 which serves the same function as that described in relation to FIG. 4.

Referring again to FIG. 4, main assembly output signal 97 will generally feed the vehicle telephony equipment. Additional output 107 may be used to feed the entertainment audio system for automatic level and spectrum adjustment based on cabin noise. While not desirable, it is possible that the vehicle electrical layout may dictate that the telephony and entertainment systems be tied to significantly differing ground points, with some degree of differential noise between them. If the two grounds are then tied together by common circuitry in the microphone assembly, noise could be introduced into both assembly outputs. A possible solution to this potential problem is to provide a partially ground-isolated output for one of the assembly outputs, for example, additional output 107.

FIG. 15 shows detail of one embodiment of additional output circuitry 105 which achieves this solution. Microphone element output

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signal 93 excites high-impedance output stage 189, having output impedance  $R_o$ . A local ground 191 is developed which is partially isolated by ground resistance  $R_g$  from the main microphone assembly ground 193. Ground resistance  $R_g$  should be large enough to prevent significant inter-ground current flow resulting from any expected inter-ground voltage differentials. A value of at least  $1/50$  of expected additional output load resistance should generally be adequate. For a load resistance of 1 kOhm,  $R_g$  would be at least 20 Ohms. Output resistance  $R_o$  should generally be large enough to significantly attenuate any inter-ground voltage differential-induced noise appearing on the load resistance. A reasonable minimum value of 5 times the expected load resistance would provide 15 decibels of such attenuation. A factor of 100 times or more would generally be preferable. For a load resistance of 1 kOhm,  $R_o$  should generally be at least 5 kOhms with 100 kOhms or more ordinarily being preferable.

It should be understood, of course, that the foregoing description refers only to a subset of the possible embodiments of the invention and that modifications or alterations may be made therein without departing from the spirit or scope of the invention as set forth in the appended claims.

What is claimed and desired to be secured by Letters Patent is:



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CLAIMS

1. A microphone assembly providing substantial response to an incident sound wave over a range of angle of arrival theta and over at least a frequency range from a lower first frequency to an upper second frequency, said first and second frequencies corresponding  
5 respectively to a first and a second wavelength, said assembly comprising:

at least two microphones having a microphone directionality, each of said at least two microphones generating an electrical microphone signal corresponding to said incident sound wave;

10 circuitry for generating at least one pattern signal from the electrical microphone signals, one of said at least one pattern signal exhibiting a pickup pattern which varies according to said angle of arrival theta substantially uniformly over said frequency range, said pickup pattern approximately equal to the microphone directionality  
15 modified by a factor of  $1 - B + B \cdot \cos(\theta)$ ; and

at least one filter for attenuating frequency components of said at least one pattern signal which are lower than said lower first frequency.

2. The microphone assembly according to claim 1, wherein said at least two microphones are spaced apart by at least one spacing distance which is not less than  $1/5$  of said second wavelength multiplied by said constant B.

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3. The microphone assembly according to claim 2 wherein said at least one spacing distance is not less than  $1/3$  nor greater than  $4/5$  of said second wavelength multiplied by said constant B.
4. The microphone assembly according to claim 1 wherein said at least one filter is a high-pass filter of at least second order.
5. The microphone assembly according to claim 4 wherein said filter shapes the frequency response above said second frequency.
6. A microphone assembly according to claim 1 wherein the microphone directionality of said at least two microphones is substantially omnidirectional.
7. A plurality of microphone assemblies according to claim 1 acoustically coupled to a common volume of space and further including a microphone assembly selector, said selector applying variable gain or attenuation to outputs of said microphone assemblies
- 5 as a function of acoustical inputs to said assemblies.
8. A microphone assembly according to claim 1, further comprising an additional output, said additional output comprised solely of any one of said electrical microphone signals.
9. A microphone assembly providing substantial response to an incident sound wave over a range of angle of arrival  $\theta$  and over at least a frequency range from a lower first frequency to an upper second frequency, said first and second frequencies corresponding

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- 5 respectively to a first and a second wavelength, said assembly comprising:
- at least two microphones having a microphone directionality which is substantially omnidirectional, each of said at least two microphones generating an electrical microphone signal corresponding
- 10 to said incident sound wave;
- said at least two microphones spaced apart by at least one spacing distance and positioned on a microphone side of an acoustical barrier, said barrier of a size having at least one dimension which is greater than said second wavelength and providing substantial
- 15 attenuation of acoustical coupling to said microphone side from an opposite side of said barrier over at least said frequency range, each of said at least two microphones having a diaphragm acoustically coupled through at least one acoustical opening to said opposite side of said barrier, each of said at least one acoustical opening constructed so as to
- 20 prevent substantial acoustical coupling from said microphone side of said barrier directly to said diaphragm;
- circuitry for generating at least one pattern signal from the microphone signals, one of said at least one pattern signal exhibiting a pickup pattern which varies according to said angle theta substantially
- 25 uniformly over said frequency range, said pickup pattern approximately equal to  $1 - B + B \cdot \cos(\theta)$  within a volume of space acoustically coupled to two of said diaphragms.

10. The microphone assembly according to claim 9 further comprising at least one filter for attenuating frequency components of said at least one pattern signal which are lower than said lower first frequency.

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each of said upper cutoff frequencies is higher than said second frequency.

18. A microphone assembly according to claim 17 wherein a ratio of said first frequency to each of said lower cutoff frequencies is greater than 5.

19. A microphone assembly according to claim 17 wherein a ratio of said first frequency to a difference between each of said lower cutoff frequencies is greater than 5.

20. A microphone assembly according to claim 17 wherein said circuitry includes at least two roll-off filters for attenuating said at least two microphone signals at frequencies below at least one roll-off corner frequency, and responsively producing at least two rolled-off  
5 signals, said at least one roll-off corner frequency lying above each of said lower cutoff frequencies of said microphones.

21. A microphone assembly according to claim 20 wherein said circuitry effectively produces at least one difference of said at least two rolled-off signals.

22. A microphone assembly according to claim 20 wherein said circuitry includes at least one delay for electrically delaying at least one of said at least two rolled-off signals and responsively producing at least one delayed signal.

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23. A microphone assembly according to claim 22 wherein said circuitry effectively produces a difference of said at least one delayed signal and at least one of said at least two rolled-off signals.

24. A microphone assembly according to claim 22 wherein said at least one delay includes an all-pass filter.

25. A microphone assembly according to claim 22 wherein said at least one delay includes a low-pass filter.

26. A microphone assembly according to claim 21 wherein at least one gain applied to at least one of said at least two rolled-off signals in said circuitry is adjustable.

27. A microphone assembly according to claim 23 wherein at least one gain applied to at least one of said at least one delayed signal and at least one of said at least two rolled-off signals in said circuitry is adjustable.

28. A plurality of microphone assemblies according to claim 9 acoustically coupled to a common volume of space and further including a microphone assembly selector, said selector applying at least one of variable gain and attenuation to outputs of said microphone  
5 assemblies as a function of acoustical inputs to said assemblies.

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29. The microphone assembly according to claim 9 further comprising an additional output, said additional output comprised solely of any one of said microphone signals.

30. The microphone assembly according to claim 17 further comprising an additional output, said additional output comprised of any one of said microphone signals and exhibiting substantial response at frequencies substantially lower than said first frequency.

31. The microphone assembly according to claim 29 wherein said at least one pattern signal is developed relative to a ground, and said additional output is developed relative to a local ground, said local ground connected to said ground by a ground resistance, said ground  
5 resistance exhibiting a resistance of greater than  $1/50$  of an expected load resistance, and wherein said additional output is developed with an output impedance, said output impedance having a value of greater than 5 times said expected load resistance.

32. The microphone assembly according to claim 30 wherein said at least one pattern signal is developed relative to a ground, and said additional output is developed relative to a local ground, said local ground connected to said ground by a ground resistance, said ground  
5 resistance exhibiting a resistance of greater than  $1/50$  of an expected load resistance, and wherein said additional output is developed with an output impedance, said output impedance having a value of greater than 5 times said expected load resistance.

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33. A microphone assembly providing substantial response to an incident sound wave over a range of angle of arrival theta and over at least a frequency range from a lower first frequency to an upper second frequency, said first and second frequencies respectively  
5 corresponding to a first and a second wavelength, said assembly comprising:

first, second and third microphones, each having a microphone directionality, said first, second and third microphones generating, respectively, first, second and third electrical microphone signals  
10 corresponding to said incident sound wave;

said first and second microphones spaced apart by a first spacing distance;

said first and third microphones spaced apart by a second spacing distance;

15 first circuitry for generating a first pattern signal from said first electrical microphone signal and said second electrical microphone signal, said first pattern signal exhibiting a pickup pattern which varies according to said angle of arrival theta substantially uniformly over said frequency range, said first pickup pattern approximately equal to  
20 said microphone directionality modified by a factor of  $1 - B + B \cdot \cos(\theta)$ ;

second circuitry for generating a second pattern signal from said first electrical microphone signal and said third electrical microphone signal, said second pattern signal exhibiting a pickup  
25 pattern which varies according to said angle of arrival theta and an offset angle phi substantially uniformly over said frequency range, said second pickup pattern approximately equal to said microphone directionality modified by a factor of  $1 - C + C \cdot \cos(\theta + \phi)$ ;

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second frequency, said first and second frequencies respectively  
5 corresponding to a first and a second wavelength, said assembly  
comprising:

first, second and third microphones, each having a microphone  
directionality which is substantially omnidirectional, each of said first,  
second and third microphones generating respectively, first, second  
10 and third electrical microphone signals corresponding to said incident  
sound wave;

said first and second microphones having first and second  
diaphragms, respectively, said first and second microphones spaced  
apart by a first spacing distance and positioned on a microphone side of  
15 an acoustical barrier, said barrier of a size having at least one  
dimension which is greater than said second wavelength and providing  
substantial attenuation of acoustical coupling to said microphone side  
from an opposite side of said barrier over at least said frequency range,  
said first and second diaphragms acoustically coupled through at least  
20 one acoustical opening to said opposite side of said barrier, said at least  
one acoustical opening constructed so as to prevent substantial  
acoustical coupling from said microphone side of said barrier directly  
to said first and second diaphragms;

said third microphone having a third diaphragm, said first and  
25 third microphones spaced apart by a second spacing distance and  
positioned on said microphone side of said barrier, said third  
diaphragm acoustically coupled through at least one acoustical opening  
to said opposite side of said barrier, said at least one acoustical opening  
constructed so as to prevent substantial acoustical coupling from said  
30 microphone side of said barrier to said third diaphragm;

first pattern generating circuitry for generating a first pattern signal from said first electrical microphone signal and said second electrical microphone signal, said first pattern signal exhibiting a pickup pattern which varies according to said angle of arrival theta substantially uniformly over said frequency range, said first pickup pattern approximately equal to  $1 - B + B \cdot \cos(\theta)$  within a volume of space acoustically coupled to said first and second diaphragms.

40. The microphone assembly according to claim 39 and further including at least one filter for attenuating frequency components of said first and second pattern signals which are lower than said first frequency.

42. The microphone combination assembly according to claim 39 wherein said at least one opening acoustically couples to said opposite

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side of said acoustical barrier through acoustically semi-transparent material.

43. The microphone assembly according to claim 39, wherein said first spacing distance is not less than  $1/5$  of said second wavelength multiplied by said constant B and said second spacing distance is not less than  $1/5$  of said second wavelength multiplied by said constant C.

44. The microphone assembly according to claim 43 wherein said first spacing distance is not less than  $1/3$  nor greater than  $4/5$  of said second wavelength multiplied by said constant B and said second spacing distance is not less than  $1/3$  nor greater than  $4/5$  of said second wavelength multiplied by said constant C.

45. The microphone assembly according to claim 40 wherein said at least one filter is a high-pass filter of at least second order.

46. The microphone assembly according to claim 45 wherein said at least one filter shapes a frequency response above said first frequency.

47. The microphone assembly according to claim 39 wherein each of said first, second, and third microphones exhibits a substantially flat frequency response over a range of frequencies from a respective lower cutoff frequency to a respective upper cutoff frequency, and wherein each of said lower cutoff frequencies is lower than said first frequency and each of said upper cutoff frequencies is higher than said second frequency.

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48. The microphone assembly according to claim 47 wherein a ratio of said first frequency to each of said lower cutoff frequencies is greater than 5.

49. The microphone assembly according to claim 47 wherein a ratio of said first frequency to the difference between any two of said lower cutoff frequencies is greater than 5.

50. The microphone assembly according to claim 47 wherein said first and second pattern generating circuitry includes first, second, and third roll-off filters for attenuating said first, second, and third microphone signals at frequencies below a roll-off corner frequency, and responsively producing first, second, and third rolled-off signals, said roll-off corner frequency lying above each of said lower cutoff frequencies.

51. The microphone assembly according to claim 50 wherein said first pattern generating circuitry effectively produces a difference of said first and second rolled-off signals and said second pattern generating circuitry effectively produces a difference of said first and third rolled-off signals.

52. The microphone assembly according to claim 50 wherein said first and second pattern generating circuitry includes a delay for electrically delaying said first rolled-off signal and responsively producing a delayed signal.

**Figure 6**

**Figure 6**

**Figure 6**

**Figure 6**

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59. A plurality of microphone assemblies according to claim 58 acoustically coupled to a common volume of space.

60. The microphone assembly according to claim 39 further comprising an additional output, said additional output comprised solely of any one of said first, second, and third microphone signals.

61. The microphone assembly according to claim 47 further comprising an additional output, said additional output comprised solely of any one of said first, second, and third electrical microphone signals and exhibiting substantial response at frequencies substantially  
5 lower than said first frequency.

62. The microphone assembly according to claim 60 wherein said first and second pattern signals are developed relative to a ground, and said additional output is developed relative to a local ground, said local ground connected to said ground by a ground resistance, said ground  
5 resistance exhibiting a resistance of greater than  $1/50$  of an expected load resistance, and wherein said additional output is developed with an output impedance, said output impedance having a value of greater than 5 times said expected load resistance.

63. The microphone assembly according to claim 61 wherein said first and second pattern signals are developed relative to a ground, and said additional output is developed relative to a local ground, said local ground connected to said ground by a ground resistance, said ground  
5 resistance exhibiting a resistance of greater than  $1/50$  of an expected

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load resistance, and wherein said additional output is developed with an output impedance, said output impedance having a value of greater than 5 times said expected load resistance.

64. A microphone assembly comprising:

at least two microphones, each of said at least two microphones receiving sound energy and generating electrical signals corresponding to the sound energy received;

5 signal processing circuitry, said signal processing circuitry processing the electrical signals into an assembly output signal; and  
said at least two microphones and said signal processing circuitry being configured to limit adverse effects on the assembly output signal from amplitude and phase mismatches between the at  
10 least two microphones.

65. The microphone assembly according to claim 64 further comprising a case for housing said at least two microphones and said signal processing circuitry.

66. The microphone assembly according to claim 65 wherein the case is mounted on a mounting side of an acoustical barrier.

67. The microphone assembly according to claim 66 wherein the acoustical barrier comprises an interior surface of a passenger vehicle.

68. The microphone assembly according to claim 66 further comprising at least one sealing gasket located between said case and the mounting side of the acoustical barrier.

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69. The microphone assembly according to claim 65 further comprising at least two sealing members which seal the at least two microphones to at least two acoustical openings in the case.

70. The microphone assembly according to claim 65 further comprising at least two protective screens located between an inner surface of the case and the at least two microphones.

71. The microphone assembly according to claim 66 further comprising a covering located on at least a portion of a pick-up side of the acoustical barrier.

72. A microphone assembly providing substantial response to an incident sound wave over at least a frequency range from a lower first frequency to an upper second frequency, said assembly comprising:

at least two microphones, each of said at least two microphones  
5 generating an electrical microphone signal corresponding to the incident sound wave;

circuitry for generating at least one pattern signal from the electrical microphone signals; and

at least one filter for attenuating frequency components of the at  
10 least one pattern signal which are lower than the lower first frequency.

73. The microphone assembly according to claim 72 wherein said at least one filter is a high-pass filter of at least second order.

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74. The microphone assembly according to claim 72 wherein the assembly provides substantial response to the incident sound wave over a range of angle of arrival  $\theta$ , and one of the at least one pattern signal exhibits a pickup pattern which varies according to the angle of arrival  $\theta$  substantially uniformly over the frequency range, the pickup pattern approximately equal to a microphone directionality modified by a factor of  $1-B+B*\cos(\theta)$ .

75. The microphone assembly according to claim 74 comprising two pattern signals, and wherein one of the two pattern signals exhibits a pickup pattern which varies according to the angle of arrival  $\theta$  and an offset angle  $\phi$  substantially uniformly over the frequency range, the pickup pattern approximately equal to a microphone directionality modified by a factor of  $1-C+C*\cos(\theta + \phi)$ .

76. The microphone assembly according to claim 72, further comprising an additional output, said additional output solely comprised of any one of the electrical microphone signals.

77. The microphone assembly according to claim 74 wherein two of said at least two microphones are spaced apart by a spacing distance which is not less than  $1/5$  of a second wavelength, corresponding to the upper second frequency, multiplied by the constant B.

78. The microphone assembly according to claim 75 wherein two of said at least two microphones are spaced apart by a spacing distance which is not less than  $1/5$  of a second wavelength, corresponding to the upper second frequency, multiplied by the constant C.

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79. A microphone assembly providing substantial response to an incident sound wave over at least a frequency range from a lower first frequency to an upper second frequency, said assembly comprising:
- at least two microphones, each of said at least two microphones
- 5 generating an electrical microphone signal corresponding to the incident sound wave; and
- said at least two microphones spaced apart by at least one spacing distance and positioned on a microphone side of an acoustical barrier, the barrier of a size having at least one dimension which is
- 10 greater than a wavelength corresponding to the upper second frequency and providing substantial attenuation of acoustical coupling to the microphone side from an opposite side of the barrier over at least the frequency range, each of said at least two microphones having a diaphragm acoustically coupled through at least one acoustical opening
- 15 to the opposite side of said barrier, each of the at least one acoustical opening constructed so as to prevent substantial acoustical coupling from the microphone side of said barrier directly to the diaphragm.

80. The microphone assembly according to claim 79 further comprising circuitry for generating at least one pattern signal from the microphone signals and wherein the assembly provides substantial response to the incident sound wave over a range of angle of arrival
- 5 theta, one of said at least one pattern signal exhibiting a pickup pattern which varies according to the angle theta substantially uniformly over the frequency range, the pickup pattern approximately equal to  $1-B+B*\cos(\theta)$  within a volume of space acoustically coupled to two of the diaphragms.

81. The microphone assembly according to claim 80 comprising two pattern signals, and wherein one exhibits a pickup pattern which varies according to the angle of arrival  $\theta$  and an offset angle  $\phi$  substantially uniformly over the frequency range, the pickup pattern approximately equal to a microphone directionality multiplied by a factor of  $1 - C + C \cdot \cos(\theta + \phi)$  within a volume of space acoustically coupled to two of said diaphragms.

82. The microphone assembly according to claim 79 wherein the diaphragms are positioned parallel to the barrier.

83. The microphone assembly according to claim 79 further comprising at least one filter for attenuating frequency components of the at least one pattern signal which are lower than the lower first frequency.

84. A microphone assembly for use in a passenger vehicle comprising:

at least two microphones, each of said at least two microphones having a diaphragm; and

5           said at least two microphones being spaced apart by at least one spacing distance and positioned on a microphone side of an acoustical barrier, each of the diaphragms being acoustically coupled through at least one acoustical opening for each diaphragm to an opposite side of the barrier, each of said at a least one acoustical opening constructed to  
10       limit acoustical coupling from the microphone side of the barrier directly to the diaphragm.

5

5

5

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87. The microphone assembly according to claim 86 wherein the opening in the case sealing gasket is of greater size than the opening in the case.

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88. The microphone assembly according to claim 86 wherein the opening in the mounting sealing gasket is of greater size than the opening in the case and the opening in the acoustical barrier.

89. The microphone assembly according to claim 86 further comprising a protective screen located between the case sealing gasket and the inner surface of the case.

90. The microphone assembly according to claim 86 further comprising a covering on at least a portion of the outer surface of the acoustical barrier.

91. A microphone assembly providing substantial response to an incident sound wave over at least a frequency range from a lower first frequency to an upper second frequency, said assembly comprising:

at least two microphones, each of said at least two microphones  
5 generating an electrical microphone signal corresponding to the incident sound wave, each of said at least two microphones exhibiting a substantially flat frequency response over a range of frequencies from a respective lower cutoff frequency to a respective upper cutoff frequency, each of the lower cutoff frequencies being lower than the  
10 first frequency and each of the upper cutoff frequencies being higher than the second frequency; and

circuitry for attenuating the microphone signals at frequencies below at least one roll-off corner frequency, and responsively producing at least two rolled-off signals, said at least one roll-off  
15 corner frequency lying above each of the respective lower cutoff frequencies of said microphones.

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92. The microphone assembly of claim 91 wherein the circuitry comprises at least two roll-off filters.

93. A microphone assembly for mounting behind an interior surface of a vehicle comprising:

- two omnidirectional microphone elements, each of said
- 5 omnidirectional microphone elements being at least substantially acoustically sealed from a mounting side of the surface and acoustically coupled to a pickup side of the surface, said omnidirectional microphone elements together creating a directional pickup pattern on the pickup side of the surface.

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#### ABSTRACT OF THE DISCLOSURE

A directional microphone assembly suitable for subsurface mounting. A directional pickup pattern is developed from the outputs of a plurality of omnidirectional microphone elements mounted in an assembly behind a surface such that their acoustic excitation comes from the opposite side of the surface through small openings in the surface. The openings may have varying dimensions and may be covered with acoustically semi-transparent material without significantly degrading the assembly frequency response or polar pattern. Precautions are taken to ensure design robustness considering practical microphone element characteristics and potential high levels of low-frequency excitation.

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FIG. 14

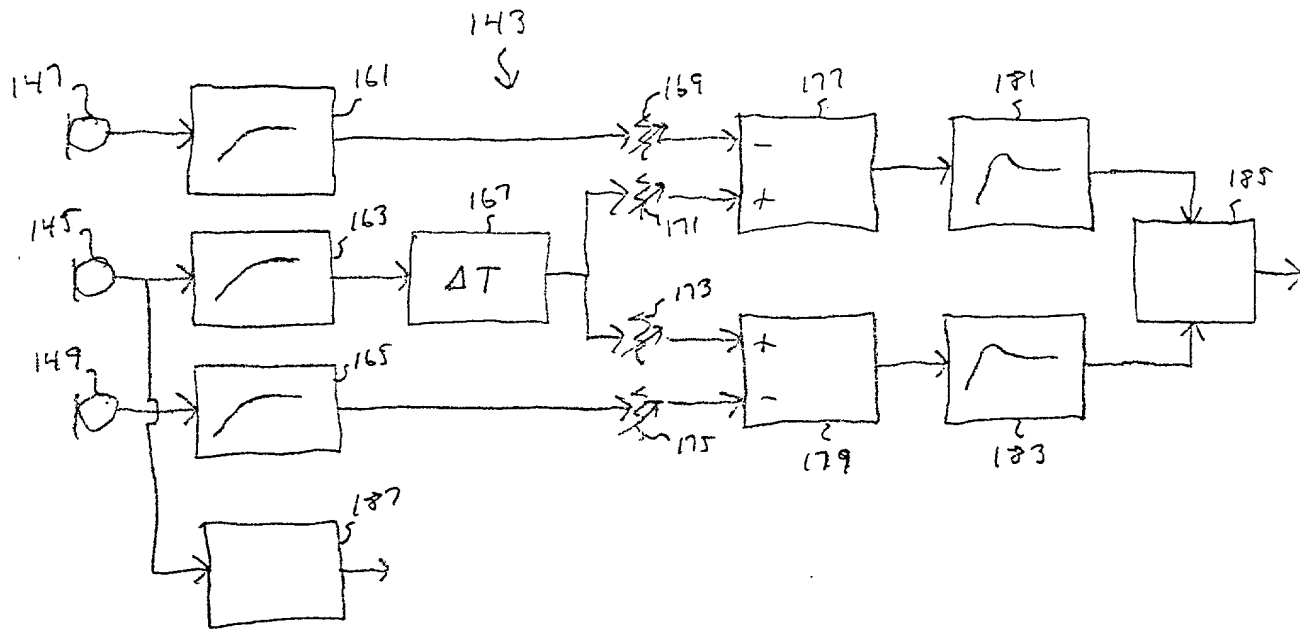
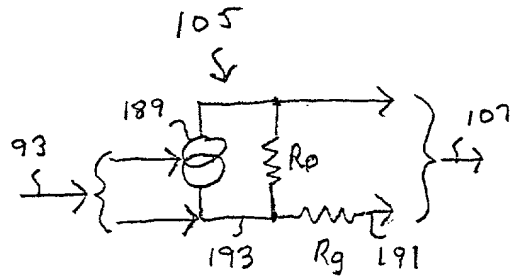
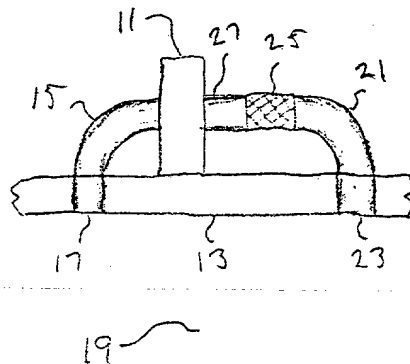


FIG. 15



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FIG. 1



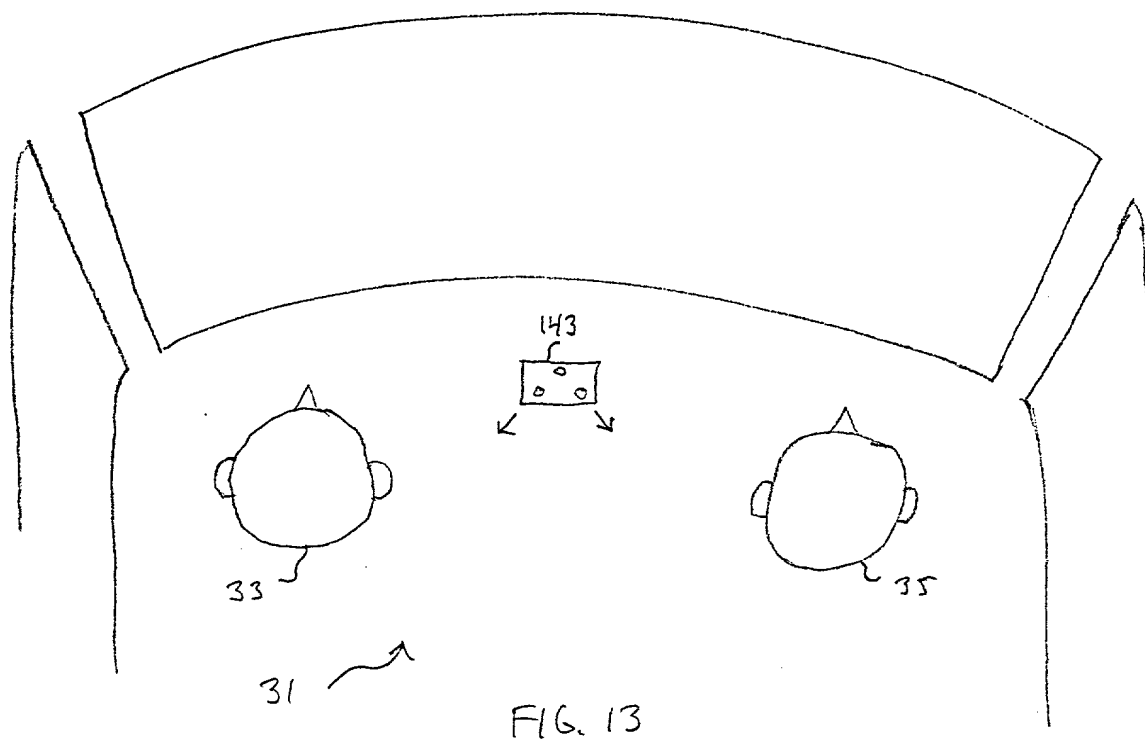
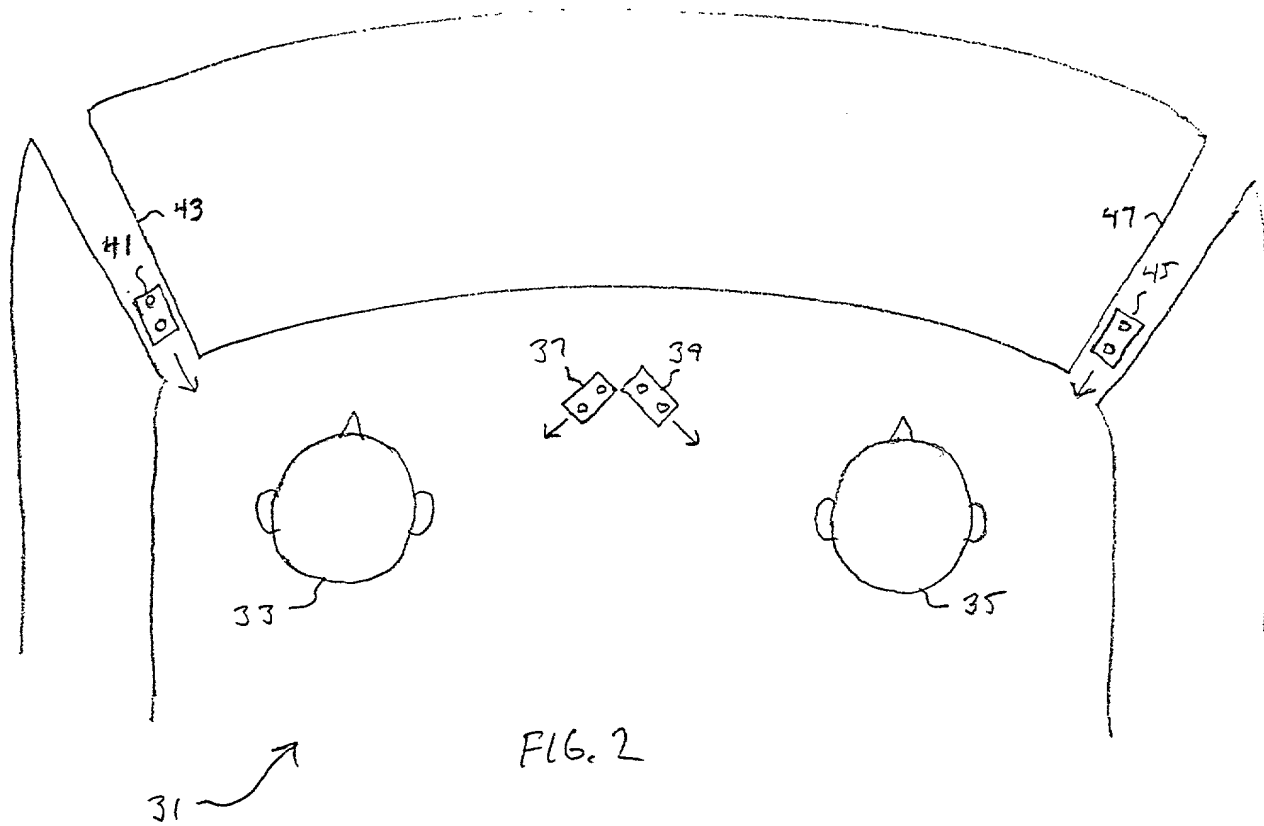
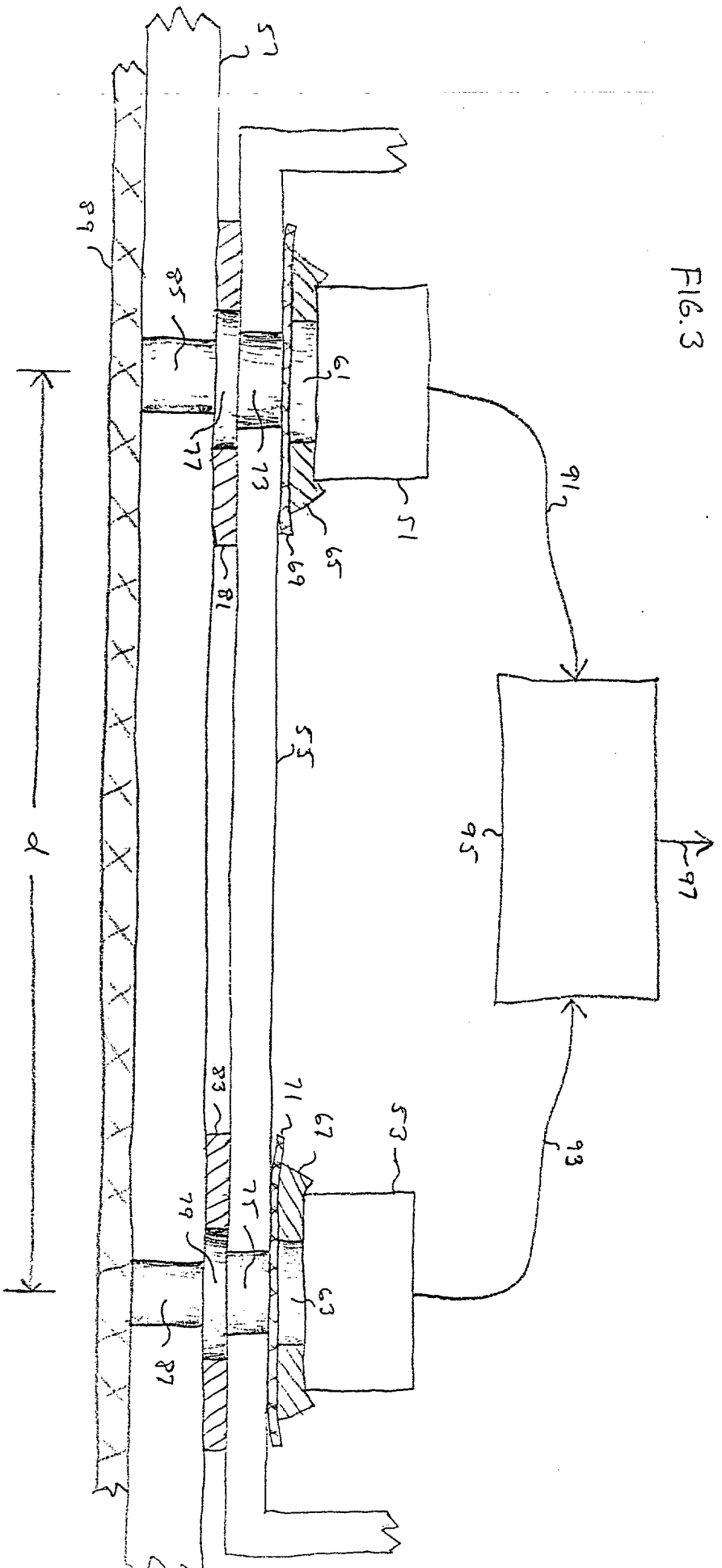


FIG. 3



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FIG. 4

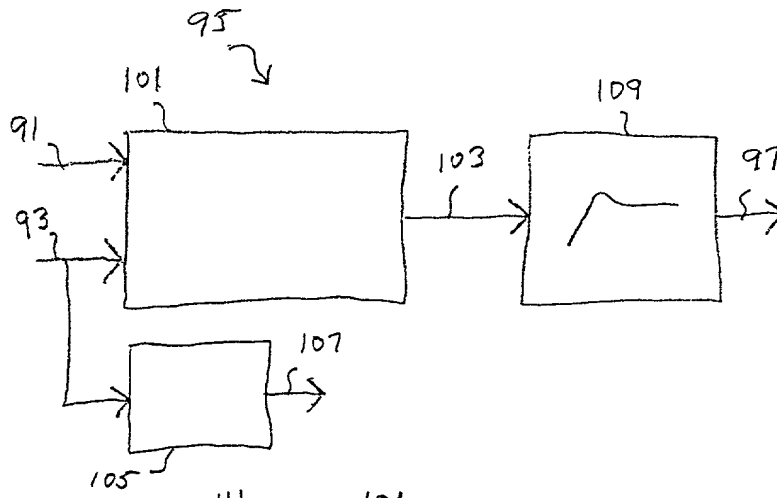


FIG. 7

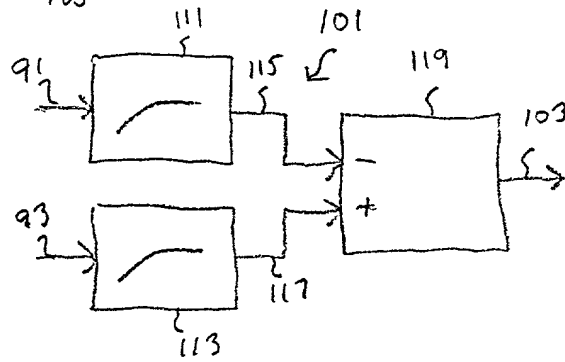


FIG. 8

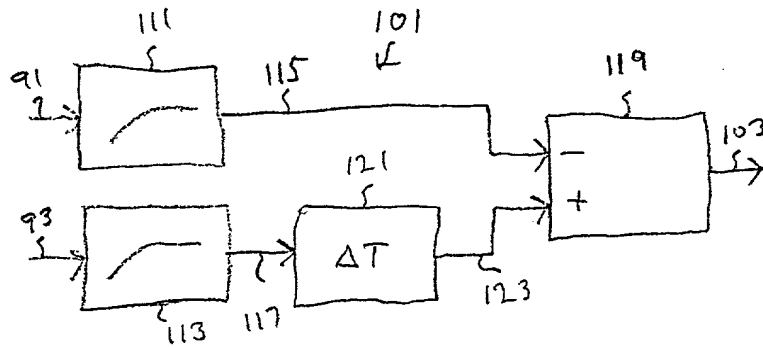
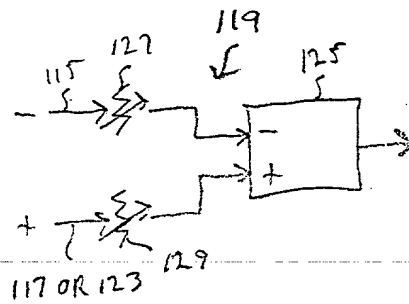
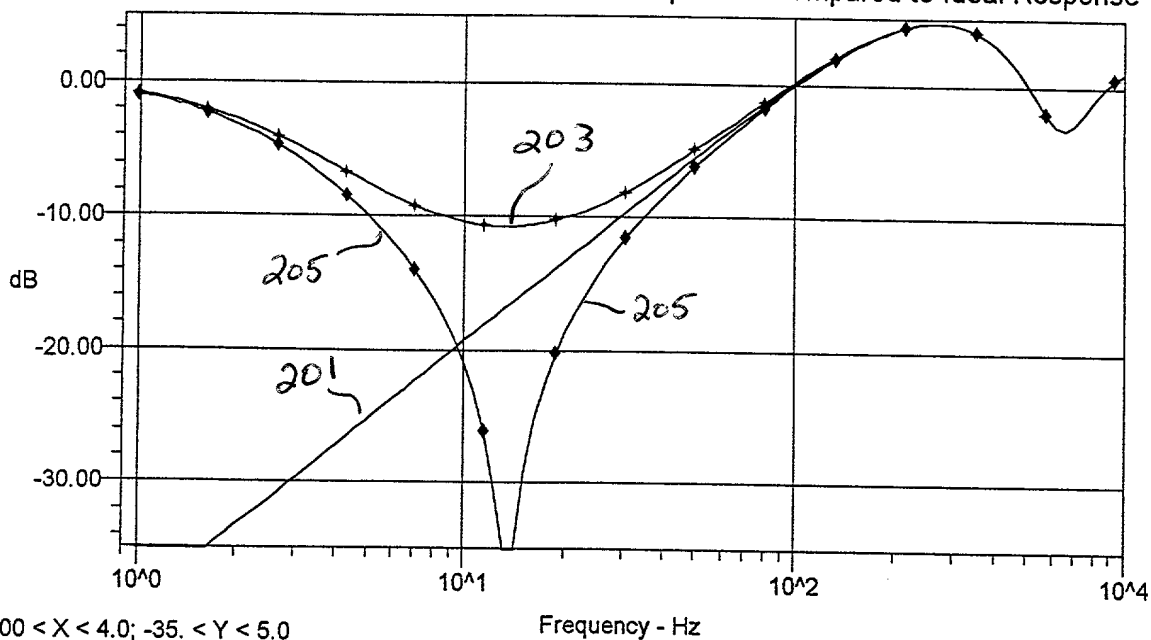


FIG. 9



On-Axis Response; +, - 20 Hz Corner Mismatch Responses Compared to Ideal Response

FIG. 5



On-Axis Eq'd Response; +, - 20 Hz Corner Mismatch Responses Compared to Ideal Response

FIG. 6

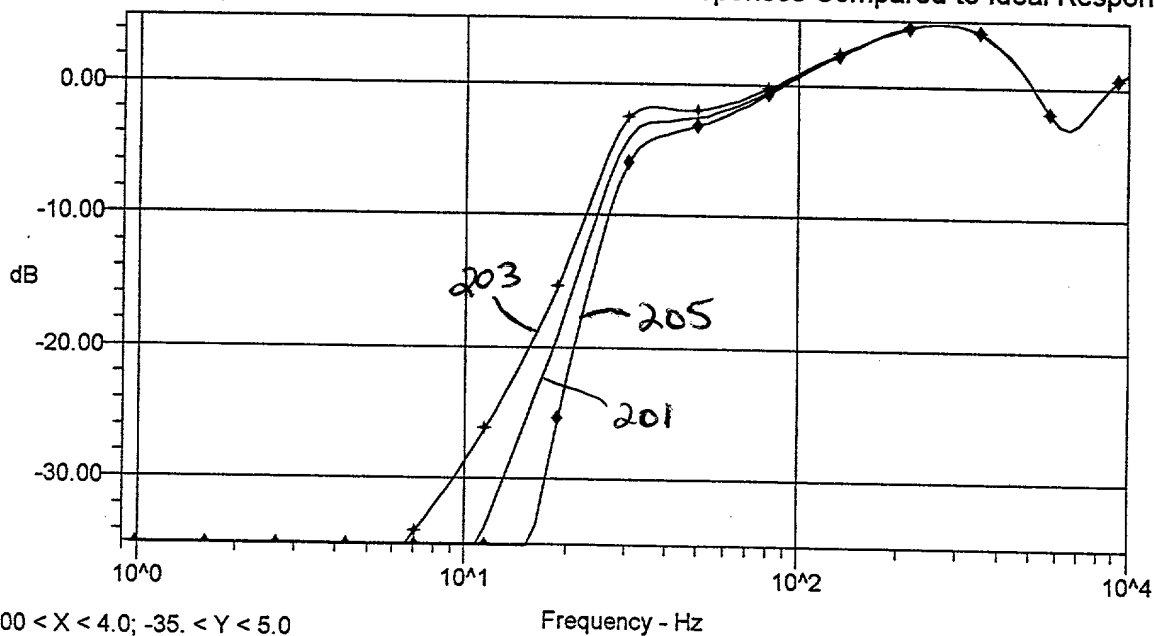


FIG. 10

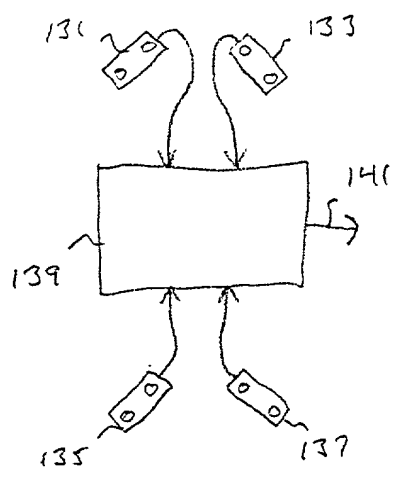


FIG. 11

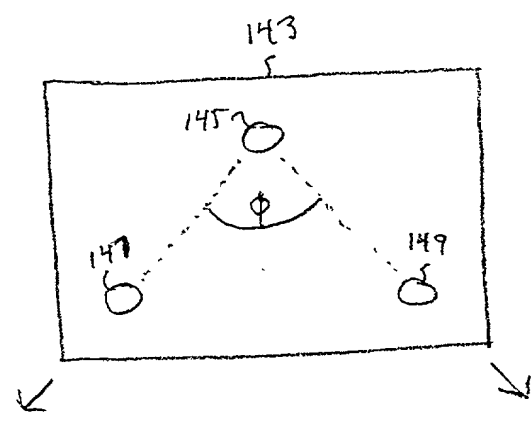
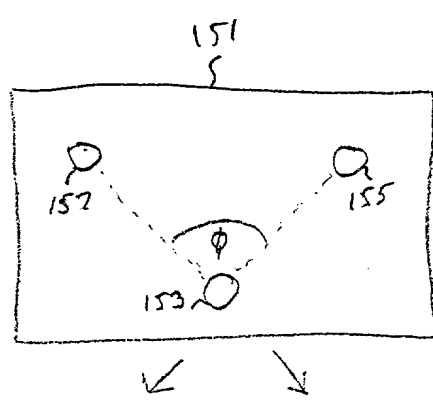


FIG. 12



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D. David Hill	Reg. No. 35,543
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Priscilla F. Gallagher	Reg. No. 32,223
Stephen F. Sherry	Reg. No. 30,590
Patrick J. Arnold Jr.	Reg. No. 37,769
Robert B. Polit	Reg. No. 33,993
George Wheeler	Reg. No. 28,766

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Ronald E. Larson	Reg. No. 24,478
Christopher C. Winslade	Reg. No. 36,308
Edward A. Mas II	Reg. No. 37,179
Gregory C. Schodde	Reg. No. 36,668
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Donald J. Pochopien	Reg. No. 32,167
Sharon A. Hwang	Reg. No. 39,717
David D. Headrick	Reg. No. 40,642
Dean D. Small	Reg. No. 34,730
Kirk A. Vander Leest	Reg. No. 34,036
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Jeffrey D. Hsi	Reg. No. 40,024

We hereby declare that all statements made herein of our own knowledge are true and that all statements made on information and belief are believed to be true; and further that these statements were made with the knowledge that willful false statements and the like so made are punishable by fine or imprisonment, or both, under Section 1001 of Title 18 of the United States Code and that such willful false statements may jeopardize the validity of the application or any patent issued thereon.

Full name of first inventor Stephen D. Julstrom

Inventor's signature \_\_\_\_\_ Date \_\_\_\_\_

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